

## Today:

- Using interpolation error bounds (HW4)
  - Cubic splines
- 

[4]

Suppose that  $f \in C^2([x_0, x_1])$  for  $x_0 < x_1$ , and let  $P(x)$  be the linear interpolant for  $f$  at  $x_0$  and  $x_1$ . Using the theorem given in class on the error in polynomial interpolation, derive the following bound:

$$|f(x) - P(x)| \leq \frac{1}{8} h^2 \max_{x \in [x_0, x_1]} |f''(x)|,$$

where  $h = x_1 - x_0$ .

$$f(x) = P(x) + \frac{f''(\xi(x))}{2} (x-x_0)(x-x_1)$$

$$\begin{aligned} |f(x) - P(x)| &= \left| \frac{f''(\xi(x))}{2} (x-x_0)(x-x_1) \right| \\ &\leq \frac{1}{2} \max_{t \in [x_0, x_1]} |f''(t)| \max_{x \in [x_0, x_1]} |(x-x_0)(x-x_1)| \end{aligned}$$

$$\begin{aligned} h(x) &= (x-x_0)(x-x_1) \\ &= x^2 - (x_0+x_1)x + x_0x_1 \end{aligned}$$

$$h'(x) = 2x - (x_0 + x_1) = 0$$

$$\Rightarrow x^* = \frac{x_0 + x_1}{2}$$

$$|h(x^*)| = \left| \left( \frac{x_0 + x_1}{2} - x_0 \right) \left( \frac{x_0 + x_1}{2} - x_1 \right) \right|$$

$$= \left| \left( \frac{x_1 - x_0}{2} \right) \left( \frac{x_0 - x_1}{2} \right) \right|$$

$$\frac{x_1 - x_0}{2} = h$$

$$= \frac{h^2}{4}$$

Check  $h(x)$  at endpoints  $x_0, x_1$

$$|f(x) - P(x)| \leq \frac{1}{2} \max_{x \in [x_0, x_1]} |f''(x)| \cdot \frac{h^2}{4}$$

$$= \frac{1}{8} h^2 \max_{x \in [x_0, x_1]} |f''(x)|$$

[5]

Suppose one seeks a polynomial approximation for  $e^{-x}$  for  $x \in [0, 1]$  using *equispaced* interpolation nodes. Using the result given in Lecture 13 for the error in polynomial interpolation for this particular case, what is the fewest number of points that will ensure

$$\max_{x \in [0,1]} |f(x) - P(x)| \leq 1 \times 10^{-6} ?$$

$$\max_{x \in [0,1]} |f(x) - P(x)| \leq \frac{1}{4} \frac{M}{n+1} h^{n+1}$$

$$M = \max_{x \in [0,1]} |f^{(n+1)}(x)| = 1$$

$$h = \frac{1}{n}$$

$$f^{(n+1)}(x) = \pm e^{-x}$$

$$\frac{1}{4} \frac{M}{n+1} h^{n+1} < 1 \cdot 10^{-6}$$

## Cubic splines

Given:

$$x_0, \dots, x_n \\ f(x_0), \dots, f(x_n)$$

Want piecewise  $S(x)$  so that:

$S(x)$  is cubic on each subinterval

$$[x_i, x_{i+1}]$$

$S(x)$  is "sufficiently smooth"

( $\Rightarrow S(x)$  continuous)

$S'(x)$  continuous

$S''(x)$  "

More concretely: Given  $x_0, \dots, x_n, f(x_0), \dots, f(x_n)$

We want  $a_j, b_j, c_j, d_j$  ( $j = 0, \dots, n$ )

$$S(x) = \begin{cases} a_0 + b_0(x - x_0) + c_0(x - x_0)^2 + d_0(x - x_0)^3 & \text{on } [x_0, x_1] \\ \vdots \\ S_i(x) = \begin{cases} a_i + b_i(x - x_i) + c_i(x - x_i)^2 + d_i(x - x_i)^3 & \text{on } [x_i, x_{i+1}] \end{cases} \end{cases}$$

$$S_{n-1}(x) = a_{n-1} + b_{n-1}(x - x_{n-1}) + c_{n-1}(x - x_{n-1})^2 + d_{n-1}(x - x_{n-1})^3$$

$$h_j = x_{j+1} - x_j$$

$$a_j = f(x_j) \quad j=0, \dots, n$$

$$a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 = a_{j+1}$$

$$b_j + 2c_j h_j + 3d_j h_j^2 = b_{j+1}, \quad j=0, \dots, n-1$$

$$c_j + 3d_j h_j = c_{j+1}, \quad j=0, \dots, n-1$$

"Natural" cubic spline:  $S'(x) = 0$  at  $a, b$   
 $c_0 = 0, c_n = 0$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ h_0 & 2(h_0+h_1) & h_1 & 0 & \cdots & 0 \\ 0 & h_1 & 2(h_1+h_2) & h_2 & \cdots & 0 \\ & & & & & \\ & & h_{n-2} & 2(h_{n-2}+h_{n-1}) & h_{n-1} & 0 \\ & & & & & 1 \end{bmatrix} \quad (n+1) \times (n+1)$$

$$\vec{c} = \begin{bmatrix} c_0 \\ \vdots \\ c_n \end{bmatrix} \quad \vec{f} = \begin{bmatrix} \frac{3}{h_1}(a_2 - a_1) + \frac{3}{h_0}(a_1 - a_0) \\ \vdots \\ \frac{3}{h_{n-1}}(a_n - a_{n-1}) + \frac{3}{h_{n-2}}(a_{n-2} - a_{n-3}) \end{bmatrix}$$

Ex/ Given:  $\{(0,1), (1,3), (2,2)\}$

Construct the "natural" cubic spline through these points.

Sols       $a_0 = f(x_0) = 1$       In this case,  
                 $a_1 = f(x_1) = 3$        $h_j = 1 \forall j$   
                 $a_2 = f(x_2) = 2$

Matrix for  $e_j$ :

$$\begin{bmatrix} 1 & 0 & 0 \\ h_0 & 2(h_0 + h_1) & h_1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 4 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\vec{f} = \begin{bmatrix} 0 \\ \frac{3}{h_1}(a_2 - a_1) + \frac{3}{h_0}(a_1 - a_0) \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -9 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 4 & 1 \\ 0 & 0 & 1 \end{bmatrix} \vec{c} = \begin{bmatrix} 0 \\ -9 \\ 0 \end{bmatrix}$$

$$c_0 = 0, c_1 = -\frac{9}{4}, c_2 = 0 \quad d_0 = \frac{-3}{4}$$

$C^2$  constraints equations:

$$c_0 + 3d_0 h_0 = c_1 \rightarrow 3d_0 = -\frac{9}{4}$$

$$c_1 + 3d_1 h_1 = c_2 \rightarrow -\frac{9}{4} + 3d_1 = 0$$

$$\Rightarrow d_1 = \frac{3}{4}$$

Continuity constraint equations:

$$a_0 + b_0 h_0 + c_0 h_0^2 + d_0 h_0^3 = a_1$$

$$a_1 + b_1 h_1 + c_1 h_1^2 + d_1 h_1^3 = a_2$$

$$b_0 = \frac{11}{4}, \quad b_1 = \frac{7}{2}$$

$$S_0(x) = 1 + \frac{11}{4}(x-0) + 0(x-0)^2 - \frac{3}{4}(x-0)^3$$

$$S_1(x) = 3 + \frac{1}{2}(x-1) - \frac{9}{4}(x-1)^2 + \frac{3}{4}(x-1)^3$$

$$S(x) = \begin{cases} S_0(x) & x \in [0, 1] \\ S_1(x) & x \in [1, 2] \end{cases}$$


---

Continuous:

$$S_0(x_1) = S_1(x_1) \quad \cancel{x(h_0)}$$

$$S_0(x_1) = a_0 + b_0(x_1 - x_0) + c_0(x-x_0)^2 + d_0(x_1 - x_0)^3$$