Today;

- . HWS comments
- · Extrapolation
- · Numerical integration leguadrature
- · Hand back midterms

Huss  
1) "diegonally dominant" A,  
WTS: A R invertible  
Suppose 3 × 6 112" \$\$ with ×70"  
s.t.  
A× = 0  
For instance, look at 1<sup>st</sup> component of 0  

$$ZA_{1j} \times j = 0$$
  
 $z$  verificant for absolute values,  
 $\Delta = 0$   
For instance, look at 1<sup>st</sup> component of 0  
 $ZA_{1j} \times j = 0$   
 $z$  verificant for absolute values,  
 $\Delta = 0$   
 $z$  invertify  
2. Proceedise-likear polynomials  
(s " connect the dots"  
8.b)  $z := 1 \frac{c_2 - \varepsilon_1}{2}$   
 $z$  (coal', find value of h that  
windimizes evert

Extrapolation



Et The backward-difference formula can be  
expressed as  
$$f'(x_0) = \frac{h[f(x_0) - f(x_0 - h)]}{h[f(x_0) - f(x_0)]} + \frac{h}{2}f''(x_0) - \frac{h^2}{6}f''(x_0) + O(h^3)}{\frac{error}{6}f''(x_0)}$$
  
Use extrapolation to derive an O(h<sup>3</sup>) formula for  
 $f'(x_0)$ .

Solu 3 constrants: 1 
$$f'(t_0)$$
  
0  $O(h^2)$ 

-> 3 different step sizes Method! N(h) = 1 [f(Xo) - f(to-h)] Phugin stepsizes: h, hiz, hig  $f'(k_{0}) = N(h_{0}) + \frac{h}{2}f''(k_{0}) - \frac{h^{2}}{6}f''(k_{0}) + O(h_{0})$  $f'(k_{0}) = N(h_{0}) + \frac{h}{24}f''(k_{0}) - \frac{h^{2}}{24}f''(k_{0}) + O(h_{0})$ f(xo) = N(hy) + h/gf"(xo) - h~ f""(xo) +0(h)  $(a+b+c)f'(x_0) = a N(h)+b n(h/z)+c N(h/y) + \left[\frac{ah}{2} + \frac{bh}{4} + \frac{ch}{5}\right]f''(x_0)$  $+ \left[ \frac{-ah^2}{6} - \frac{bh^2}{24} - \frac{ch^2}{96} \right] f''(x_0)$ toch<sup>s</sup>) (Another option:) Eatore constrants: (h, 2h, 4h)  $\frac{ah}{2} + \frac{bh}{3} + \frac{ch}{3} = 0 - 2 - \frac{a}{2} + \frac{b}{3} + \frac{c}{3} = 0$  $-\frac{ah^{2}}{6} - \frac{bh^{2}}{2y} - \frac{ch^{2}}{96} = 0 \rightarrow \frac{a}{6} - \frac{b}{2y} - \frac{c}{76} = 0$ 

Matrix form:  

$$\begin{bmatrix}
\frac{1}{2} & \frac{1}{2} & \frac{1}{3} \\
\frac{1}{2} & \frac{1}{2} & \frac{1}{3} \\
\frac{1}{2} & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} \\
\frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\
\frac{1}{2} & \frac{1}{3} & \frac{1}{3} \\
\frac{1}{2} & \frac{1}{3} & \frac{1}{3} \\
\frac{1}{3} & \frac{1}{3} \\
\frac{1}{3}$$

New method.

 $f(x_{0}) = \frac{1}{2}N(h) - 2N(\frac{h}{2}) + \frac{8}{3}N(\frac{h}{3}) + O(h^{3})$ 

Numerical Integration / Quadvature

Trapezoidal rule:  

$$\int_{a}^{b} f(t) dx = \frac{b-a}{2} (f(a) + f(b)) frule$$

$$= -\frac{1}{12} f''(3) (b-a)^{3} ferror$$

Using the trapezoidal rule. Find an error bound and compare to the actual absolute error, given that  $\pi_y$  $\int x \sin(x) dx \approx 0.1517769$ 

Sola: Rue:

Try  $\int x \sin(x) dx \approx \frac{\pi y}{2} \left( \frac{\sigma(x)}{\tau} \right)^{-1}$ = 0.2180895

## to compute onor bound, we mant to find mak [f"(-S)] geE0,#74]

> compute f''(X) to find max (sult) + cos(x)) < 2

Ex Find 
$$c_0, c_1, x_1$$
 so the formula  

$$\int_{0}^{1} f(x) dx \approx e_0 f(0) + e_1 f(x_1)$$
has the highest possible degree of etactness.  
Iden: integration is linear  
booky need to check monomizeds  
Soly: Plug in monomizets:  

$$\int_{0}^{1} 1 dx = 1 = c_0 \cdot 1 + c_1 \cdot 1$$

$$1 = c_0 + c_1$$

$$\int_{0}^{1} x dx = \frac{1}{2} = c_0 (0) + c_1 x_1$$

$$\frac{1}{2} = c_1 x_1$$

$$\int_{0}^{1} x^2 dx = \frac{1}{3} = c_0 (0)^2 + c_1 (t_1)^2$$

$$\frac{1}{2} = c_1 (x_1)^2$$

$$x_1 = \frac{2}{3}, \quad c_1 = \frac{3}{4}, \quad c_0 = \frac{1}{4}$$

$$\int_{0}^{1} 1(t_1) dx \approx \frac{1}{4} f(0) + \frac{5}{4} f(\frac{2}{3})$$

 $\int \sqrt{3} dx = \frac{1}{4} \int but$  $\frac{1}{4} (0)^{3} + \frac{3}{7} (\frac{2}{5})^{3} = \frac{2}{9}$ → D.O.E. = )

Et The quadrature formula  

$$\int_{-1}^{1} f(x) dx \approx e_0 f(-1) + c_1 f(0) + c_2 f(1)$$

is exact for polynomicals of degree  $\leq 2$ . Find  $C_0, C_1, C_2$ .